

# Collaborative likelihood-ratio estimation over graphs

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# Likelihood-ratio and statistics

## Definition

Consider a feature space  $\mathcal{X} \subset \mathbb{R}^n$  and two probability distributions  $P$  and  $Q$  ( $Q \ll P$ ) such that they admit density functions  $p(x)$  and  $q(x)$  with respect to  $dx$ , then the **likelihood-ratio** is defined as:

$$r(x) = \frac{q(x)}{p(x)} \quad x \in \mathcal{X}$$

## Applications

- ▶ *Hypothesis Testing* (Neyman-Pearson Lemma [[Neyman et al., 1933](#)])
- ▶ *Sequential Change-point detection* [[Page, 1954](#), [Shiryaev, 1963](#)]
- ▶ *Transfer Learning* (Importance sampling [[Fishman, 1996](#)])

# Existing methods

## Usual non-parametric approach

$r(\cdot)$  is the solution of an optimization problem defined in terms of a functional space  $\mathbb{H}$  (RKHS) [Nguyen et al., 2008a, Sugiyama et al., 2012]

## Single source or Data aggregation



**What about multiple interrelated sources of data?**

## Indicative use-cases

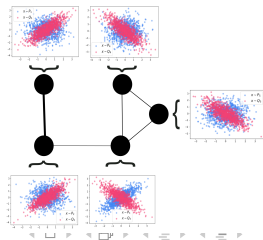
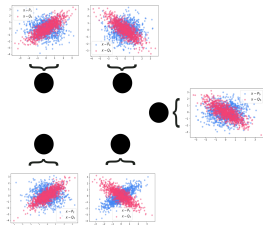
- Spatial statistics and learning:  
e.g. Monitoring geophysical phenomena using a sensor network, public health surveillance, transport network analysis,

# Motivation and main contribution

- 1 Local information can be important and **data aggregation** may hide phenomena of interest
- 2 **Ignoring inter-dependencies** may lead to a weaker performance than a multitasking approach

## Main contribution

*Graph-based Relative Unconstrained Least-Squares Importance Fitting (GRULSIF)*: a framework addressing both limitations by integrating a graph component into the estimation of multiple likelihood-ratios



# Problem statement

**Question** How to infer a vector of likelihood-ratio functions

$\mathbf{r}(X) = (r_1(x_1), \dots, r_N(x_N))$   
from interrelated data sources?

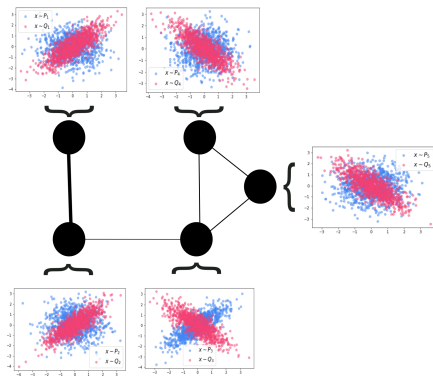
## Setting

- ▶  $G = (V, E, W)$  is a known weighted undirected graph, and  $W$  is a matrix encoding *node similarities*

- ▶ Each node  $v \in V$  has batch access to observations

$$x_1, x_2, \dots, x_n \stackrel{\text{iid}}{\sim} P_v \text{ and}$$

$$x'_1, x'_2, \dots, x'_{n'} \stackrel{\text{iid}}{\sim} Q_v$$

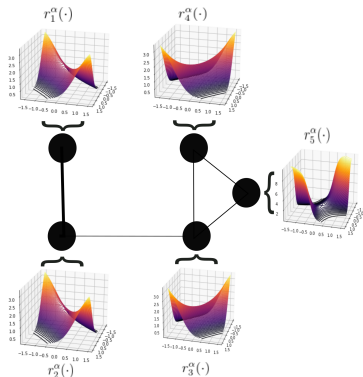


**Figure:** Example of different interrelated sources of information. In this case  $\mathcal{X} = \mathbb{R}^2$

# Problem statement

## Framework

- ▶ Infer the node-level relative likelihood-ratios
$$r_v^\alpha(\cdot) = \frac{q_v(\cdot)}{(1-\alpha)p_v(\cdot) + \alpha q_v(\cdot)}$$
- ▶ Non-parametric estimation based on a kernel function  $K(\cdot, \cdot) : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}^+$  to avoid making hypotheses on the nature of  $q_v(\cdot)$  and  $p_v(\cdot)$
- ▶ Capitalize over the information provided apriori by the graph:
$$\|r_u - r_v\|_{\mathbb{H}} < \epsilon \quad \text{if} \quad W_{uv} \neq 0$$



**Figure:** We aim to estimate the set of functions  $\{r_v^\alpha(\cdot)\}_{v \in V}$  by exploiting  $G = (V, E)$

# Application: Collaborative two-sample testing

## Problem statement

$$H_{\text{null}} : p_v = q_v, \quad \forall v \in V \quad \text{vs} \quad H_{\text{alt}} : p_v \neq q_v, \quad \forall v \in C$$

where  $C$  is a subset of nodes, such that the vector  $r^\alpha(X) = (r_1^\alpha(x), \dots, r_N^\alpha(x))$  is a smooth signal over the graph  $G$

## Potential applications:

- ① Detection of an earthquake
- ② Characterization of the nature of an epidemic
- ③ Spot regions of pollution peak

# Inference techniques

## Non-parametric estimation with a single data source

### Definition

A  $\phi$ -divergence functional quantifies the similarity between two probability measures that are described by their  $p(x)$ ,  $q(x)$  in  $X$ :

$$\mathcal{D}_\phi(P, Q) = \int p(x) \phi(r(x)) dx \geq \sup_{f \in \mathcal{F}} \int f dQ - \int \phi^*(f) dP \quad (1)$$

where  $\mathcal{F}$  is a functional space [Nguyen et al., 2008b].

If we choose the Pearson-Divergence  $\phi(x) = \frac{(x-1)^2}{2}$  and  $F = \mathbb{H}$  (RKHS), then we aim to infer the likelihood-ratio  $r(\cdot)$  by solving:

$$\min_{f \in \mathbb{H}} \int \frac{f^2(x)}{2} dP(x) - \int f(x) dQ(x)$$



# Inference techniques

## Multitasking formulation of the problem

By the reproduction property of  $\mathbb{H}$ , for each  $v \in V$ ,  $f_v$  takes the form:

$$f_v(x) = \sum_{l=1}^L \theta_{v,l} K(x, x_l)$$

Then we estimate the vector-valued function  $f = (f_1, \dots, f_N) \in \mathbb{H}^N$  under the hypothesis that  $\theta_u$  and  $\theta_v$  are expected to be similar if nodes  $u$  and  $v$  are connected in  $G$ :

$$\begin{aligned} \min_{\Theta \in \mathbb{R}^{NL}} \frac{1}{N} \sum_{v \in V} \frac{\mathbb{E}_{p_v^\alpha(x)} [(r_v^\alpha(x) - f_v(x))^2]}{2} &+ \frac{\lambda \gamma}{2} \sum_{v \in V} \|\theta_v\|^2 \\ &+ \frac{\lambda}{2} \sum_{u, v \in V} W_{uv} \|\theta_u - \theta_v\|^2 \end{aligned}$$

# Main results and contribution [\[de la Concha et al., 2022\]](#)

## ① GRULSIF: Graph-based Relative Unconstrained Least-Squares Importance Fitting

- A novel non-parametric framework for estimating multiple likelihood-ratios
- A detailed and efficient implementation that is conveniently scalable for big graphs

## ② Collaborative two-sample test

- A detailed procedure that includes best hyperparameters identification and p-values estimation
- A collaborative two-sample test that outperforms non-parametric approaches that does not take the graph into account:  
KLIEP [\[Sugiyama et al., 2007\]](#), ULSIF [\[Sugiyama et al., 2011\]](#)  
RULSIF [\[Yamada et al., 2011\]](#), MMD [\[Gretton et al., 2012\]](#)  
MMD aggregated [\[Schrab et al., 2021\]](#)

# Thank you

# References I

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