

# A Greedy Approach for Dynamic Control of Diffusion Processes in Networks

## Supplementary Material

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### I. INTRODUCTION

This document provides the supplementary technical material for the mentioned paper which is published in the annual *IEEE International Conference on Tools with Artificial Intelligence (ICTAI)*, 2015. This document, along with the release of the software package developed by Kevin Scaman and Argyris Kalogeratos for conducting the simulations for this work, are available at: <http://kalogeratos.com/material/lrie-dra/>.

### II. APPENDIX

The second order derivative of the number of infected nodes is computed as the sum of three derivatives:

$$\begin{aligned} \frac{d^2}{dt^2} \mathbb{E}[N_I(t)] &= -\delta \frac{d}{dt} \mathbb{E}[N_I(t)] \\ &\quad -\rho \frac{d}{dt} \mathbb{E}[X(t)^\top R(t)] \\ &\quad +\beta \frac{d}{dt} \mathbb{E}[X(t)^\top A\bar{X}(t)]. \end{aligned} \quad (2.1)$$

In the following, we show that only the third derivative  $\frac{d}{dt} \mathbb{E}[X(t)^\top A\bar{X}(t)]$  depends on  $R(t)$  when  $R(t)$  already minimizes  $\frac{d}{dt} \mathbb{E}[N_I(t)]$ . First, Eq. 4.9 shows that  $\frac{d}{dt} \mathbb{E}[N_I(t)]$  does not depend on  $R(t)$  since  $X(t)^\top R(t) = \min(b_{tot}, N_I(t))$ . Second, let  $H(t) = \min(b_{tot}, N_I(t))$ , then  $\frac{d}{dt} \mathbb{E}[X(t)^\top R(t)]$  can be computed as follows:

$$\frac{d}{dt} \mathbb{E}[X(t)^\top R(t)] = \lim_{\Delta t \rightarrow 0} \frac{\mathbb{E}[H(t+\Delta t)] - \mathbb{E}[H(t)]}{\Delta t}. \quad (2.2)$$

Let  $\Delta t$  be a sufficiently small time interval. Three scenarios are possible:

- either  $N_I(t) > b_{tot}$  and, during  $t' \in [t, t + \Delta t]$ ,  $H(t')$  is stationary (since  $N_I(t')$  can at most increase or decrease by one),
- either  $N_I(t) < b_{tot}$  and  $H(t') = N_I(t')$  during  $\Delta t$ ,
- or the last possibility is  $N_I(t) = b_{tot}$ , and in this case we only have to consider the case where  $N_I(t + \Delta t) = b_{tot} - 1$  ( $H(t')$  will not change if  $N_I(t)$  increases).

Let  $\mathbb{1}_{\{c\}} \in \mathbb{R}^N$  be a vector with unit values at dimensions where a certain *condition*  $c$  is true, and

$\bar{X}(t) = \mathbb{1} - X(t)$  be the vector indicating the healthy nodes of the network. We can then write:

$$\begin{aligned} \mathbb{E}[H(t + \Delta t)|X(t)] &= \mathbb{1}_{\{N_I(t) > b_{tot}\}} b_{tot} \\ &\quad + \mathbb{1}_{\{N_I(t) = b_{tot}\}} [b_{tot} - \delta N_I(t)\Delta t - \rho X(t)^\top R(t)\Delta t] \\ &\quad + \mathbb{1}_{\{N_I(t) < b_{tot}\}} [N_I(t) - \delta N_I(t)\Delta t - \rho X(t)^\top R(t)\Delta t \\ &\quad \quad \quad + \beta X(t)^\top A\bar{X}(t)\Delta t] \\ &\quad \quad \quad + o(\Delta t) \\ &= H(t) \\ &\quad - \mathbb{1}_{\{N_I(t) \leq b_{tot}\}} [\delta N_I(t) + \rho H(t)]\Delta t \\ &\quad + \mathbb{1}_{\{N_I(t) < b_{tot}\}} \beta X(t)^\top A\bar{X}(t)\Delta t \\ &\quad + o(\Delta t). \end{aligned} \quad (2.3)$$

We thus have:

$$\begin{aligned} \frac{d}{dt} \mathbb{E}[X(t)^\top R(t)] &= \lim_{\Delta t \rightarrow 0} \frac{\mathbb{E}[\mathbb{E}[H(t+\Delta t)|X(t)]] - \mathbb{E}[H(t)]}{\Delta t} \\ &= -\mathbb{E}[\mathbb{1}_{\{N_I(t) \leq b_{tot}\}} (\delta N_I(t) + \rho H(t))] \\ &\quad + \mathbb{E}[\mathbb{1}_{\{N_I(t) < b_{tot}\}} \beta X(t)^\top A\bar{X}(t)], \end{aligned} \quad (2.4)$$

which does not depend on  $R(t)$ .

Finally,  $\frac{d}{dt} \mathbb{E}[X(t)^\top A\bar{X}(t)]$  is the only term depending on  $R(t)$  (using Eq. 4.7 and Eq. 4.8):

$$\begin{aligned} \frac{d}{dt} \mathbb{E}[X(t)^\top A\bar{X}(t)] &= \sum_{i,j} A_{ij} \frac{d}{dt} \mathbb{E}[X_i(t)\bar{X}_j(t)] \\ &= \sum_{i,j} A_{ij} \left( \frac{d}{dt} \mathbb{E}[X_i(t)] - \frac{d}{dt} \mathbb{E}[X_i(t)X_j(t)] \right) \\ &= -\delta \sum_{i,j} A_{ij} \mathbb{E}[X_i(t)] \\ &\quad -\rho \sum_{i,j} A_{ij} \mathbb{E}[X_i(t)R_i(t)] \\ &\quad +\beta \sum_{i,j,k} A_{ij} A_{ki} \mathbb{E}[\bar{X}_i(t)X_k(t)] \\ &\quad +2\delta \sum_{i,j} A_{ij} \mathbb{E}[X_i(t)X_j(t)] \\ &\quad +\rho \sum_{i,j} A_{ij} \mathbb{E}[X_i(t)X_j(t)(R_i(t) + R_j(t))] \\ &\quad -\beta \sum_{i,j,k} A_{ij} A_{ki} \mathbb{E}[\bar{X}_i(t)X_j(t)X_k(t)] \\ &\quad -\beta \sum_{i,j,k} A_{ij} A_{kj} \mathbb{E}[X_i(t)\bar{X}_j(t)X_k(t)]. \end{aligned} \quad (2.5)$$

This equation is simplified by the fact that, in order to minimize  $\frac{d}{dt} \mathbb{E}[N_I(t)]$ , resources are only given to infected nodes, which implies  $X_i(t)R_i(t) = R_i(t)$ . We can thus

rewrite this derivative as:

$$\begin{aligned}
& \frac{d}{dt} \mathbb{E}[X(t)^\top A \bar{X}(t)] \\
&= -\rho \sum_{i,j} A_{ij} \mathbb{E}[R_i(t)] \\
&\quad + \rho \sum_{i,j} A_{ij} \mathbb{E}[X_j(t) R_i(t) + X_i(t) R_j(t)] \\
&\quad + \Xi(t) \\
&= -\rho \mathbb{E}[\mathbf{1}^\top A^\top R(t)] \\
&\quad + \rho \mathbb{E}[X(t)^\top A^\top R(t) + X(t)^\top A R(t)] \\
&\quad + \Xi(t) \\
&= -\rho \mathbb{E}[\{A \bar{X}(t) - A^\top X(t)\}^\top R(t)] \\
&\quad + \Xi(t),
\end{aligned} \tag{2.6}$$

where  $\Xi(t)$  is independent of  $R(t)$ . This leads to the second order derivative of  $\mathbb{E}[N_I(t)]$  given in Eq. 4.11.